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0.1

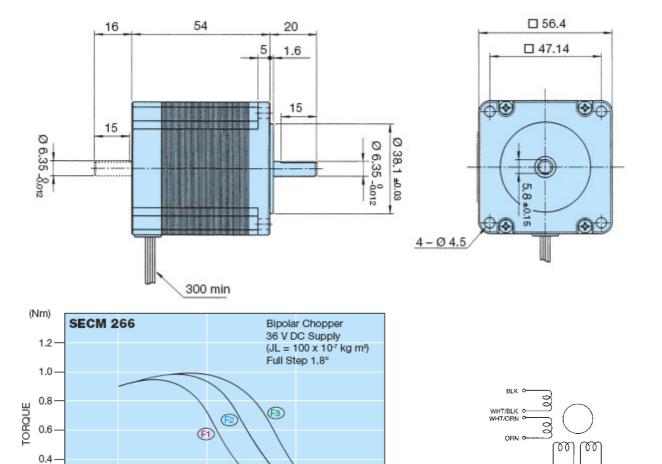
SECM266... Series

2-Phase-Stepping Motor [1,8° High-Torque-Version]

Model	Bipolar Parallel				Bipolar Serial				Unipolar				Torque
A = Single Shaft B = Double Shaft	Holding Torque	Current/ Phase	Phase	Inductance/ Phase	Holding Torque	Current/ Phase	Resistance/ Phase	Phase	Holding Torque	Phase	Resistance/ Phase	Phase	Speed- curve
	[Nm]	[A]	[Ohm]	[mH]	[Nm]	[A]	[Ohm]	[mH]	[Nm]	[A]	[Ohm]	[mH]	
SECM266-E1.0 (A/B)	1.17	1.4	3.6	11.0	1.17	0.7	14.4	44.0	0.90	1.0	7.2	11.0	[1]
SECM266-E2.0 (A/B)	1.17	2.8	0.9	2.5	1.17	1.4	3.6	10.0	0.90	2.0	1.8	2.5	F 2
SECM266-E3.0 (A/B)	1.17	4.2	0.4*	1.2	1.17	2.1	1.6*	4.8	0.90	3.0	0.8*	1.2	F 3

Number of Leads	Weight of Motor	Size Lenght	Rotor Inertia
8	0.7 kg	56.4 x 56.4 x 54 mm	260 x 10 ⁻⁷ kgm²

Resistance / Phase (Ω) = \pm 10%, (* \pm 15%), Inductance / Phase (mH) = \pm 20%





SPEED

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(KPPS)



Planetary Gears / Encoders are optionally available

