



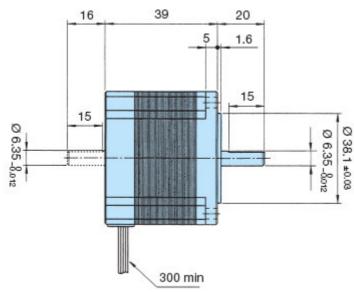
## SECM264... Series

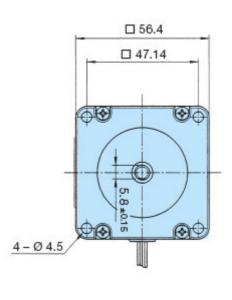
2-Phase-Stepping Motor [1,8° High-Torque-Version]

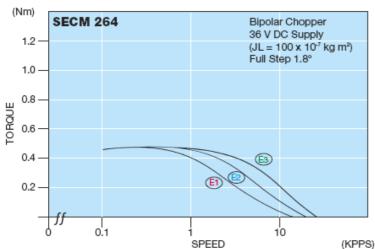
Model	Bipolar Parallel				Bipolar Serial				<ul><li>Unipolar</li></ul>				Torque Speed-
A = Single Shaft B = Double Shaft	Holding Torque	Current/ Phase	Resistance/ Phase	Inductance/ Phase	Holding Torque	Current/ Phase	Resistance/ Phase	Inductance/ Phase	Holding Torque	Current/ Phase	Resistance/ Phase	Inductance/ Phase	curve
	[Nm]	[A]	[Ohm]	[mH]	[Nm]	[A]	[Ohm]	[mH]	[Nm]	[A]	[Ohm]	[mH]	
SECM264-E1.0 (A/B)	0.50	1.4	2.6	5.4	0.50	0.7	10.4	21.6	0.39	1.0	5.2	5.4	Œ1
SECM264-E2.0 (A/B)	0.50	2.8	0.7	1.4	0.50	1.4	2.8	5.6	0.39	2.0	1.4	1.4	<b>E</b> 2
SECM264-E3.0 (A/B)	0.50	4.2	0.3*	0.5	0.50	2.1	1.2*	2.0	0.39	3.0	0.6*	0.5	<b>(E2)</b>

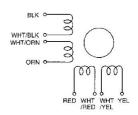
Number of Leads	Weight of Motor	Size Lenght	Rotor Inertia
8	0.45 kg	56.4 x 56.4 x 39 mm	120 x 10 <sup>-7</sup> kgm²

Resistance / Phase ( $\Omega$ ) =  $\pm$  10%, (\*  $\pm$  15%), Inductance / Phase (mH) =  $\pm$  20%









Planetary Gears / Encoders are optionally available

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